Ministry of Higher Education and Scientific Research Scientific Supervision and Scientific Evaluation Apparatus Directorate of Quality Assurance and Academic Accreditation Accreditation Department



# Academic Program and Course Description Guide

# Introduction:

The educational program is a well-planned set of courses that include procedures and experiences arranged in the form of an academic syllabus. Its main goal is to improve and build graduates' skills so they are ready for the job market. The program is reviewed and evaluated every year through internal or external audit procedures and programs like the External Examiner Program.

The academic program description is a short summary of the main features of the program and its courses. It shows what skills students are working to develop based on the program's goals. This description is very important because it is the main part of getting the program accredited, and it is written by the teaching staff together under the supervision of scientific committees in the scientific departments.

This guide, in its second version, includes a description of the academic program after updating the subjects and paragraphs of the previous guide in light of the updates and developments of the educational system in Iraq, which included the description of the academic program in its traditional form (annual, quarterly), as well as the adoption of the academic program description circulated according to the letter of the Department of Studies T 3/2906 on 3/5/2023 regarding the programs that adopt the Bologna Process as the basis for their work.

In this regard, we can only emphasize the importance of writing an academic programs and course description to ensure the proper functioning of the educational process.

1

# **Concepts and terminology:**

<u>Academic Program Description</u>: The academic program description provides a brief summary of its vision, mission and objectives, including an accurate description of the targeted learning outcomes according to specific learning strategies.

<u>Course Description</u>: Provides a brief summary of the most important characteristics of the course and the learning outcomes expected of the students to achieve, proving whether they have made the most of the available learning opportunities. It is derived from the program description.

**<u>Program Vision</u>**: An ambitious picture for the future of the academic program to be sophisticated, inspiring, stimulating, realistic and applicable.

**<u>Program Mission</u>**: Briefly outlines the objectives and activities necessary to achieve them and defines the program's development paths and directions.

**<u>Program Objectives</u>**: They are statements that describe what the academic program intends to achieve within a specific period of time and are measurable and observable.

<u>Curriculum Structure</u>: All courses / subjects included in the academic program according to the approved learning system (quarterly, annual, Bologna Process) whether it is a requirement (ministry, university, college and scientific department) with the number of credit hours.

**Learning Outcomes:** A compatible set of knowledge, skills and values acquired by students after the successful completion of the academic program and must determine the learning outcomes of each course in a way that achieves the objectives of the program.

<u>Teaching and learning strategies</u>: They are the strategies used by the faculty members to develop students' teaching and learning, and they are plans that are followed to reach the learning goals. They describe all classroom and extra-curricular activities to achieve the learning outcomes of the program.

2

#### Academic Program Description Form

University Name: University of Technology-Iraq Faculty/Institute: Control and Systems Engineering Department Scientific Department: Mechatronics and Robotics Engineering Brunch

Academic or Professional Program Name: Bachelor of Mechatronics and **Robotics Engineering** 

Final Certificate Name: Bachelor of Science of Mechatronics and Robotics Engineering

Academic System: Semesters

**Description Preparation Date: 7/4/2024** 

File Completion Date: 7/4/2024

Signature: Saland Head of Department Name: Scientific Associate Name: Prof. pr. Abbas 14. Iss. Date: 7 /11 / Date: 7 /11 / Date: 8 /4 /2024 Date: 7 /4/ 2024

Signature: 7

Date: 8/4/2024

The file is checked by:

Department of Quality Assurance and University Performance

Director of the Quality Assurance and University Performance Department: Prof. Shayman M. Mahly Date:

Signature:

Approval of the Dean

Dr. Azad Rahee

#### 1. Program Vision

The future vision of the Mechatronics and Robotics Engineering branch within the Control and Systems Engineering Department at the University of Technology is to increase scientific knowledge of the aforementioned specialization by developing current curricula and keeping pace with emerging theoretical, practical and applied knowledge according to a vision that defines the community's need and the future industrial base of the country.

#### 2. Program Mission

Preparing specialized engineering cadres capable of serving society with high efficiency, contributing to technological development, and striving to obtain international accreditation.

#### 3. Program Objectives

1. To support the students to have a broad-based education in the basic principles of electrical, mechanical, computer engineering and robotics. Their knowledge enables them to solve a wide range of mechanical, electrical and software problems, allowing them to participate in and lead multidisciplinary design teams.

2. To prepare the students to cover multidisciplinary areas including engineering analysis and design; engineering mechanics; robotics and automatic control; signals and communication; electrical hardware and computer software.

3. To provide the students with the capability to understand and analyze engineering problems which encounter them in the workplace such as manufacturers in industry, in the aerospace and also in the defense sectors for the government and industry research groups.

4. To enhance the students to learn and solve complex problem from different fields with the team members to communicate effectively.

# 4. Program Accreditation

ABET

Iraqi Council of Accreditation for engineering education

# 5. Other external influences

Not Found

| 6. Program Struct    | ure       |              |            |          |
|----------------------|-----------|--------------|------------|----------|
| Program Structure    | Number of | Credit hours | Percentage | Reviews* |
|                      | Courses   |              |            |          |
| Institution          | 67        | 142          | 1000/      | -        |
| Requirements         | 07        | 142          | 100%       |          |
| College Requirements | 67        | 142          | 100%       | -        |
| Department           | 67        | 142          | 100%       | -        |
| Requirements         | 07        | 142          | 10070      |          |
| Summer Training      | Available | -            | -          | -        |
| Other                | -         | -            | -          | -        |

\* This can include notes whether the course is basic or optional.

| 7. Program De   | escription                                    |                               |             |              |
|-----------------|---|-------------------------------|-------------|--------------|
| Year/Level      | Course Code                                   | Course Name                   |             | Credit Hours |
|                 |   |                               | theoretical | practical    |
| 2023-2024/First | 3-2024/First DCEC111 DC Electrica<br>Circuits |                               | 3           | 2            |
| 2023-2024/First | MATH112                                       | Mathematics                   | 4           | -            |
| 2023-2024/First | COMP108                                       | Computer                      | 1           | 2            |
| 2023-2024/First | ENDR114                                       | Engineering<br>Drawing        | -           | 3            |
| 2023-2024/First | ELPH115                                       | Electronic Physics            | 3           | -            |
| 2023-2024/First | WSHE106                                       | Workshops                     | -           | 6            |
| 2023-2024/First | DEHR105                                       | Democracy and<br>Human Rights | 2           | -            |
| 2023-2024/First | ACEC121                                       | AC Electrical<br>Circuits     | 3           | 2            |
| 2023-2024/First | CALC122                                       | Calculus                      | 4           | -            |
| 2023-2024/First | COPR123                                       | Computer                      | 3           | 2            |

|                              |                  | Drogramming               |          |   |
|------------------------------|------------------|---------------------------|----------|---|
| 2022 2024/Eirot              | CAED124          | Computer Aided            |          | 2 |
| 2023-202 <del>4</del> /FIISt | CAED124          | Engineering               | -        | 5 |
|                              |                  | Drowing                   |          |   |
| 2023 2024/Eirst              | ENI A 107        | English Language          | 2        |   |
| 2023-2024/First              | WSHE106          | Workshops                 | 2        | - |
| 2023-2024/First              |                  | Uumon Dights              | -        | 0 |
| 2023-2024/Secolia            | IIUKIUIUI        | DC Electrical             | Z        | - |
| 2023-2024/ Second            | DCEMA102         | DC Electrical<br>Machines | 2        | - |
| 2022 2024/ Second            |                  | Machines                  | 2        |   |
| 2023-2024/ Second            | MECHAI03         | Digital Tachniquas        | 2        | - |
| 2023-2024/ Second            | DIGTE104         | 1                         | 3        | - |
| 2023-2024/ Second            | ELECT105         | Electronics 1             | 2        | - |
|                              |                  | Engineering               |          |   |
| 2023-2024/ Second            | ENMAT106         | Mathematics 1             | 2        | - |
| 2023-2024/ Second            | CONTH107         | Control Theory 1          | 2        | _ |
|                              |                  | Measurements and          |          |   |
| 2023-2024/ Second            | MEAIN108         | Instrumentation 1         | 2        | - |
| 2023-2024/ Second            | DYNAM110         | Dynamics 1                | 2        | _ |
|                              |                  | Engineering               | •        |   |
| 2023-2024/ Second            | ENMAT206         | Mathematics 2             | 2        | - |
| 2023-2024/ Second            | CONTH207         | Control Theory 2          | 2        | - |
| 2022 2024/ 5 1               |                  | Digital Techniques        | 2        |   |
| 2023-2024/ Second            | DIGTE204         |                           | 3        | - |
| 2023-2024/ Second            | ELECT205         | Electronics 2             | 2        | - |
| 2022 2024/ Second            |                  | AC Electrical             | 2        |   |
| 2025-2024/ Second            | ACEMIA202        | Machines                  | Z        | - |
| 2022 2024/ Second            | DDOC 200         | Programming with          | 2        |   |
| 2025-2024/ Second            | PROG209          | MATLAB                    | 2        | - |
| 2023 2024/ Second            | MEAIN108         | Measurements and          | 2        |   |
| 2023-2024/ Second            | MILAINIUO        | Instrumentation 2         | 2        | - |
| 2023-2024/ Second            | -                | Laboratories 2            | -        | 8 |
| 2023-2024/Third              | PI CO1332        | Programmable              | 2        |   |
|                              | 11001332         | Logic Controller 1        |          |   |
| 2023-2024/Third              | FCCD3302         | Electronic Circuits       | 2        | _ |
|                              | LCCD3302         | Design 1                  | 2        | _ |
| 2023-2024/Third              | MRTE1302         | Microprocessor            | 2        | _ |
|                              | MIX121302        | Techniques                | <i>L</i> |   |
| 2023-2024/Third              | FCOM1333         | Fundamentals of           | 2        | _ |
|                              | 100000555        | Communications            | 2        |   |
| 2023-2024/Third              | EANA1301         | Engineering               | 2        | _ |
|                              |                  | Analysis                  | -        |   |
| 2023-2024/Third              | COTH1306         | Control Theory 3          | 2        | - |
| 2023-2024/Third              | DYNM3354         | Dynamics 2                | 2        | - |
| 2023-2024/Third              | FLPO3353         | Fluid Power               | 2        | - |
| 2023-2024/Third              | 223-2024/Third - |                           | -        | 6 |
| 2023-2024/Third              | PLCO1332         | Programmable              | 2        | _ |
|                              | 11001332         | Logic Controller 2        | <u> </u> |   |

| 2023-2024/Third   | DSPR1339 | Digital Signal<br>Processing                               | 2 | - |
|-------------------|----------|--|---|---|
| 2023-2024/Third   | MICO1356 | Microcontrollers<br>and Embedded<br>Systems                | 2 | - |
| 2023-2024/Third   | NUAN1336 | Numerical Analysis<br>using MATLAB                         | 2 | _ |
| 2023-2024/Third   | COTH1353 | Control Theory 4   | 2 | - |
| 2023-2024/Third   | ECCD3303 | Electronic Circuits<br>Design 2                            | 2 | - |
| 2023-2024/Third   | THMA3357 | Theory of<br>Machines                                      | 2 | - |
| 2023-2024/Third   | ENMM3356 | Engineering<br>Materials and<br>Manufacturing<br>Processes | 2 | - |
| 2023-2024/Third   | -        | Laboratories 2   | - | 6 |
| 2023-2024/Fourth  | MECH4261 | Mechanical Design  | 2 | - |
| 2023-2024/ Fourth | MSDE3459 | Mechatronic<br>Systems Design 1                            | 1 | 2 |
| 2023-2024/ Fourth | COIN1405 | Computer<br>Interfacing                                    | 2 | - |
| 2023-2024/ Fourth | ROIS3464 | Robotics and<br>Intelligent Systems                        | 3 | _ |
| 2023-2024/ Fourth | DICO3460 | Digital Control  | 2 | - |
| 2023-2024/ Fourth | MOCO3462 | Modern Control 1   | 2 | - |
| 2023-2024/ Fourth | ARIR3463 | Artificial<br>Intelligence for<br>Robotics                 | 2 | - |
| 2023-2024/ Fourth | -        | Laboratories 1   | - | 2 |
| 2023-2024/ Fourth | POWE4267 | Power Electronics  | 2 | - |
| 2023-2024/ Fourth | INDE1401 | Industrial<br>Engineering                                  | 2 | - |
| 2023-2024/ Fourth | MSDE3459 | Mechatronic<br>System Design 2                             | 1 | 2 |
| 2023-2024/ Fourth | SYID3465 | System<br>Identification                                   | 2 | - |
| 2023-2024/ Fourth | ROAU3464 | Robotics and<br>Automation                                 | 3 | - |
| 2023-2024/ Fourth | GPRO3461 | Project  | 2 | 4 |
| 2023-2024/ Fourth | MOCO3462 | Modern Control 2   | 2 | - |
| 2023-2024/ Fourth | DMRO3458 | Design and<br>Manufacturing of<br>Robots                   | 2 | _ |
| 2023-2024/ Fourth | -        | Laboratories 2   | - | 2 |
|                   |          |  |   |   |

| 8. Expected learning                | outcomes of the program  |
|-------------------------------------|--|
| Knowledge                           |  |
| A1- Introducing the student to      | 1- Mid Exams   |
| mechatronics engineering            | 2- Quizez  |
| theories                            | 3- Discussions   |
| A2- Enabling the student to         | 4– Homework's  |
| know and understand the             |  |
| applications of practical           |  |
| scientific theories in the field of |  |
| mechatronics engineering            |  |
| A3- Enabling the student to         |  |
| choose optimal solutions to         |  |
| problems in the field of            |  |
| mechatronics engineering.           |  |
| Skills                              |  |
| <b>B1</b> - Analysis                | 1- Mid Exams<br>2- Ouizez  |
| <b>B2</b> – Design                  | 3- Discussions   |
| B3- Implementation                  | 4- Homework s  |
| Ethics                              |  |
| C1- Motivate and urge the           | The student's skills are evaluated by how to find the engineering    |
| student to understand and           | problem and how to find the engineering solution to it at the lowest |
| assimilate the theoretical          | cost, with the highest possible cost, and with the least possible    |
| material and encourage him to       | error.   |
| design and implement special        |  |
| engineering designs in the          |  |
| mechatronics engineering            |  |
| branch.                             |  |
| C2- Encouraging collective          |  |
| work in the form of a team          |  |
| through discussions, group          |  |
| solutions, and participation in     |  |
| the annual exhibition for the       |  |
| manufacture of special devices      |  |
| in the mechatronics engineering     |  |
| branch.                             |  |

#### 9. Teaching and Learning Strategies

- Theoretical lectures, practical laboratory experiments, preparing reports, discussion, training, scientific visits, preparing research and participating in scientific conferences and exhibitions.
- Solve mathematical problems.
- Preparing algorithms and implementing them using computers.
- Using modern software and means of communication such as the Internet for information and research.

#### **10. Evaluation methods**

- Showing Specific Problem
- Discussions
- Meetings

| 11. Faculty                       |                            |  |  |               |               |                |
|-----------------------------------|----------------------------|--|--|---------------|---------------|----------------|
| Faculty Members                   |                            |  |  |               |               |                |
| Academic Rank                     | Specializati               | on   | Special<br>Requirements<br>(if applicable) | s/Skills<br>) | Number of the | teaching staff |
|                                   | General                    | Special  |  |               | Staff         | Lecturer       |
| أ.د. سفانة مظهر رأفت محمود        | هندسة<br>السيطرة<br>والنظم | هندسة<br>سيطرة<br>واتمتة                         | _  |               |               | _              |
| أ.د. احمد ابراهيم عبد الكريم احمد | هندسة<br>السيطرة<br>والنظم | هندسة<br>الانظمة<br>الذاتية<br>والانسان<br>الالي | _  | _             | $\checkmark$  | _              |

|   | 1  |                             |   | - | Γ            | Γ |
|---|--|-----------------------------|---|---|--------------|---|
| أ.د. سليم خليفة كاظم اكسارة                 | هندسة<br>ميكانيكية                       | ميكانيك<br>حياتي            | - | - | $\checkmark$ | _ |
| أ.م.د. لمي عيسى عبد الكريم<br>علي           | هندسة<br>السيطرة<br>والنظم               | هندسة<br>ميكاترونكس         | _ | _ | $\checkmark$ | _ |
| أ.م.د. زينة خليل عبد الامير باقر            | رياضيات                                  | نظم<br>ديناميكية            | _ | _ | $\checkmark$ | _ |
| أ.م.د. حذيفة خليل ابراهيم كاظم              | هندسة<br>السيطرة<br>والنظم               | الادارة<br>الهندسية         | _ | _ | $\checkmark$ | _ |
| م.د. زينب صباح محمدامين<br>عبدعلي           | هندسة<br>السيطرة<br>والنظم               | هندسة<br>ميكانرونكس         | _ | - | $\checkmark$ | _ |
| م.د. محمد نوري رضا علي                      | هندسة<br>الانتاج<br>والمعادن             | مواد معادن                  | _ | _ | $\checkmark$ | _ |
| م.د.حيدر دعامي رسن علي                      | هندسة<br>الكترونيك<br>واتصالات           | هندسة<br>اتصالات<br>الجوالة | _ | _ | $\checkmark$ | _ |
| م.د.مهند نوفل مصطفى حمد                     | تقنيات<br>هندسة<br>السيطرة               | تقنيات<br>انظمة<br>سيطرة    | _ | _ | $\checkmark$ | _ |
| م.د. قمر قاسم محمد جواد                     | هندسة الليزر<br>والالكترونيات<br>البصرية | هندسة<br>الليزر             | _ | _ | $\checkmark$ | _ |
| <ol> <li>أ. شيماء محمود مهدي عبد</li> </ol> | هندسة<br>السيطرة<br>والنظم               | هندسة<br>ميكاترونكس         | _ | _ | $\checkmark$ | _ |
| أ.م. ایفان ایشو کو <sub>ری</sub> ں ایشو     | هندسة<br>السيطرة<br>والنظم               | هندسة<br>ميكاترونكس         | _ | _ | $\checkmark$ | _ |

| م. بيداء هاشم هلال خضير   | کهرباء<br>وتربية | هندسة<br>الكهر بائية | - | _ | $\checkmark$ | _ |
|---------------------------|------------------|----------------------|---|---|--------------|---|
|                           | 100              |                      |   |   |              |   |
| م. عبير فاضل شمال باش اغا | هندسة            | هندسة                |   |   | 1            |   |
|                           | السيطرة          | ميكاترونكس           | _ | - | $\checkmark$ | _ |
|                           | والنظم           |                      |   |   |              |   |
| م. ناهدة ناجي كاظم زبالة  | هندسة            | هندسة                |   |   |              |   |
|                           | السيطرة          | ميكاترونكس           | - | - | $\checkmark$ | - |
|                           | والنظم           |                      |   |   |              |   |
| م. بشار فاتح مدحت فضيل    | هندسة            | هندسة                |   |   |              |   |
|                           | السيطرة          | ميكاترونكس           | - | - | $\checkmark$ | - |
|                           | والنظم           |                      |   |   |              |   |
| م. ليث خميس مجيد محمد     | هندسة            | هندسة                |   |   |              |   |
|                           | السيطرة          | ميكاترونكس           | - | - | $\checkmark$ | - |
|                           | والنظم           |                      |   |   |              |   |
| م.م. سمية فليح حسن احمد   |                  | اللغة                |   |   | 1            |   |
|                           | اداب             | انكليزية             | _ | _ | N            | _ |
|                           |                  |                      |   |   |              |   |
| م.م. مازن نجيب اجاويد     | هندسة طبيان      | هندسة                | _ | _ | 2            | _ |
|                           | هدسه طيران       | سيطرة                |   |   | v            |   |
| م.م. رشا محمد ناجی ذیاب   | هندسة            | هندسة                |   |   |              |   |
|                           | السيطرة          | سطرة                 | _ | _ | $\checkmark$ | _ |
|                           | ملانظم           | <u>سي رو</u>         |   |   | ·            |   |
|                           | والتلغم          |                      |   |   |              |   |
| م.م. عمر فاضل حمد سلمان   | 1 1              | اقتصاديات            |   |   | .1           |   |
|                           | افتصاد عام       | التعليم              | _ | - | N            | _ |
|                           |                  |                      |   |   |              |   |
| م.م. عطارد خضير احمد سالم | هندسة            | هندسة                |   |   | 1            |   |
|                           | السيطرة          | ميكاترونكس           | - | - | $\checkmark$ | _ |
|                           | والنظم           |                      |   |   |              |   |
| م.م. رسل عادل کاظم جبار   | هندسة            | ميكانيك              |   |   | _1           |   |
|                           | ميكانيكية        | تطبيقي               | _ | - | N            | _ |
|                           |                  |                      |   |   |              |   |

#### **Professional Development**

#### Mentoring new faculty members

1. Enter the classroom with former faculty members for two months as an observer.

2. Contributing to publishing research in local, regional and international journals for the purpose

of fulfilling the requirements for scientific promotion.

3. Encouraging new faculty members to complete their graduate studies within their specialty.

4. Developing the faculty member's skills in teaching, learning, and managing the educational process.

5. Participation in scientific conferences, seminars, workshops and scientific exhibitions.

#### Professional development of faculty members

1. Contributing to publishing research in local, regional and international journals for the purpose of fulfilling the requirements for scientific promotion.

2. Encouraging new faculty members to complete their graduate studies within their specialty.

3. Developing the faculty member's skills in teaching, learning, and managing the educational process.

4. Participation in scientific conferences, seminars, workshops and scientific exhibitions.

#### 12. Acceptance Criterion

1- Central admission plan standard.

2- Admission of the top graduates to the institutes.

## 13. The most important sources of information about the program

Methodical books and lectures by teachers collected from various sources.

## 14. Program Development Plan

This is done through periodic review of curricula and review of scientific developments in the field of mechatronics and robotics engineering

|            |                |                                  | Pro      | ogram                              | Skills    | s Outl | ine |        |    |    |        |        |  |  |
|------------|----------------|----------------------------------|----------|------------------------------------|-----------|--------|-----|--------|----|----|--------|--------|--|--|
|            |                |                                  |          | Required program Learning outcomes |           |        |     |        |    |    |        |        |  |  |
| Year/Level | Course<br>Code | Course<br>Name                   | Basic or | Knov                               | Knowledge |        |     | Skills |    |    | Ethics | Ethics |  |  |
|            |                |                                  | optional | A1                                 | A2        | A3     |     | B1     | B2 | B3 | C1     | C2     |  |  |
| First      | DCEC111        | DC<br>Electrical<br>Circuits     | Basic    |                                    | X         |        |     | X      |    |    |        | X      |  |  |
|            | MATH112        | Mathematic s                     | Basic    | X                                  |           |        |     |        |    | X  |        |        |  |  |
|            | COMP108        | Computer                         | Basic    | X                                  |           |        |     |        | X  |    |        | X      |  |  |
|            | ENDR114        | Engineering<br>Drawing           | Basic    |                                    |           |        |     | X      |    |    |        | X      |  |  |
|            | ELPH115        | Electronic<br>Physics            | Basic    |                                    | X         |        |     |        |    | X  |        | X      |  |  |
|            | WSHE106        | Workshops                        | Basic    |                                    |           |        |     |        | X  |    |        |        |  |  |
|            | DEHR105        | Democracy<br>and Human<br>Rights | Basic    |                                    |           |        |     |        |    |    |        | X      |  |  |
|            | ACEC121        | AC<br>Electrical                 | Basic    |                                    | X         |        |     | X      |    |    |        | X      |  |  |

|        |          | Circuits                                    |       |   |   |   |   |   |   |   |   |  |
|--------|----------|---|-------|---|---|---|---|---|---|---|---|--|
|        | CALC122  | Calculus                                    | Basic | X |   |   |   |   | X |   |   |  |
|        | COPR123  | Computer<br>Programmi<br>ng                 | Basic | X |   |   |   | X |   |   | X |  |
|        | CAED124  | Computer<br>Aided<br>Engineering<br>Drawing | Basic |   |   |   | X |   |   |   | X |  |
|        | ENLA107  | English<br>Language                         | Basic |   |   |   |   |   |   |   | X |  |
|        | WSHE106  | Workshops                                   | Basic |   |   |   |   | X |   |   |   |  |
| Second | HURIG101 | Human<br>Rights                             | Basic |   |   |   |   |   |   |   | X |  |
|        | DCEMA102 | DC<br>Electrical<br>Machines                | Basic |   | X |   |   | X |   |   |   |  |
|        | MECHA103 | Mechanics                                   | Basic |   | X |   |   | X |   |   |   |  |
|        | DIGTE104 | Digital<br>Techniques                       | Basic |   | X | X |   |   |   | X |   |  |

|              | 1   |       |   |   |   |   |   |   |   |   |   |   |  |
|--------------|---|-------|---|---|---|---|---|---|---|---|---|---|--|
| ELECT105     | Electronics<br>1                              | Basic |   | X |   | X | X |   |   | X |   |   |  |
| ENMAT106     | Engineering<br>Mathematic<br>s 1              | Basic |   |   | X |   |   |   | X |   |   |   |  |
| CONTH107     | Control<br>Theory 1                           | Basic | X | X |   |   |   |   | X |   | X |   |  |
| MEAIN108     | Measureme<br>nts and<br>Instrumenta<br>tion 1 | Basic |   | X |   |   |   |   | X |   | X |   |  |
| LABR2260     | Laboratorie<br>s 1                            | Basic | X | X |   |   |   | X |   |   |   |   |  |
| DYNAM11<br>0 | Dynamics 1                                    | Basic | X |   |   |   |   |   | X |   |   | X |  |
| ENMAT206     | Engineering<br>Mathematic<br>s 2              | Basic |   |   | X |   |   |   | X |   |   |   |  |
| CONTH207     | Control<br>Theory 2                           | Basic | X | X |   |   |   |   | X |   | X |   |  |
| DIGTE204     | Digital                                       | Basic |   | X |   | X |   |   |   | X |   |   |  |

|       |          | Techniques<br>2                               |       |   |   |   |   |   |   |   |   |   |   |  |
|-------|----------|---|-------|---|---|---|---|---|---|---|---|---|---|--|
|       | ELECT205 | Electronics 2                                 | Basic |   | X |   | X | X |   |   | X |   |   |  |
|       |          | AC  | Basic |   | X |   |   |   | X |   |   |   |   |  |
|       | ACEMA202 | Electrical<br>Machines                        |       |   |   |   |   |   |   |   |   |   |   |  |
|       | PROG209  | Programmi<br>ng with<br>MATLAB                | Basic |   |   | X |   |   |   |   |   |   |   |  |
|       | MEAIN108 | Measureme<br>nts and<br>Instrumenta<br>tion 2 | Basic |   | X |   |   |   |   | X |   | X |   |  |
|       | LABR2260 | Laboratorie<br>s 2                            | Basic | X | X |   |   |   | x |   |   |   |   |  |
| Third | PLCO1332 | Programma<br>ble Logic<br>Controller 1        | Basic |   | X |   |   | X | X |   |   |   | X |  |
|       | ECCD3302 | Electronic<br>Circuits<br>Design 1            | Basic |   | X |   |   | X | X |   |   |   | X |  |

|  | MRTE1302        | Microproce   | Basic |   |   |   |   |   |   |   |   |   |  |
|--|-----------------|--------------|-------|---|---|---|---|---|---|---|---|---|--|
|  |                 | ssor         |       |   | X |   | X | X |   |   | X |   |  |
|  |                 | Techniques   |       |   |   |   |   |   |   |   |   |   |  |
|  |                 | Fundamenta   | Basic |   |   |   |   |   |   |   |   |   |  |
|  | FCOM1333        | ls of        |       |   | x |   |   |   | v |   | v |   |  |
|  | FCOMI555        | Communica    |       |   |   |   |   |   | Λ |   | Λ |   |  |
|  |                 | tions        |       |   |   |   |   |   |   |   |   |   |  |
|  | EANA 1201       | Engineering  | Basic |   |   | v |   |   | v | V |   |   |  |
|  | EANAISUI        | Analysis     |       |   |   | Λ |   |   | Λ |   |   |   |  |
|  | COTH1306        | Control      | Basic | v | v |   |   |   | v | v | Χ |   |  |
|  |                 | Theory 3     |       | Λ | Λ |   |   |   | Λ |   |   |   |  |
|  | DYNM3354        | Dynamics 2   | Basic | X |   |   |   |   | X |   | X |   |  |
|  | FLPO3353        | Fluid Power  | Basic |   |   | X |   |   | X |   |   |   |  |
|  | 1 4 0 0 2 2 6 0 | Laboratorie  | Basic |   |   |   |   |   |   |   |   |   |  |
|  | LABR3260        | s 1          |       | X | X |   |   | X |   |   |   | X |  |
|  |                 | Programma    | Basic |   | X |   | X | X |   |   | X |   |  |
|  | PLCO1332        | ble Logic    |       |   |   |   |   |   |   |   |   |   |  |
|  |                 | Controller 2 |       |   |   |   |   |   |   |   |   |   |  |
|  |                 | Digital      | Basic |   |   |   |   |   |   |   | X |   |  |
|  | DSPR1339        | Signal       |       |   | X |   |   |   | Χ |   |   |   |  |
|  |                 | Processing   |       |   |   |   |   |   |   |   |   |   |  |

|  |             | Microcontr  | Basic |   |   |   |   |   |   |  | X |  |
|--|-------------|-------------|-------|---|---|---|---|---|---|--|---|--|
|  | MICO1356    | ollers and  |       |   | v |   | v | v |   |  |   |  |
|  |             | Embedded    |       |   | Λ |   | Λ | Λ |   |  |   |  |
|  |             | Systems     |       |   |   |   |   |   |   |  |   |  |
|  |             | Numerical   | Basic |   |   |   |   |   |   |  |   |  |
|  | NITA N1336  | Analysis    |       |   |   | v |   |   | v |  |   |  |
|  | NUAN1550    | using       |       |   |   | Λ |   |   | Λ |  |   |  |
|  |             | MATLAB      |       |   |   |   |   |   |   |  |   |  |
|  | СОТИ1252    | Control     | Basic | v | v |   |   |   | v |  | X |  |
|  | 01111555    | Theory 4    |       | Λ | Λ |   |   |   | Λ |  |   |  |
|  |             | Electronic  | Basic |   | Χ |   | X | Χ |   |  | Χ |  |
|  | ECCD3303    | Circuits    |       |   |   |   |   |   |   |  |   |  |
|  |             | Design 2    |       |   |   |   |   |   |   |  |   |  |
|  | ТНМΛ3357    | Theory of   | Basic |   | v |   | v |   | v |  |   |  |
|  | TIIVIA3337  | Machines    |       |   | Λ |   | Λ |   | Λ |  |   |  |
|  |             | Engineering | Basic |   |   |   |   |   |   |  |   |  |
|  |             | Materials   |       |   |   |   |   |   |   |  |   |  |
|  | ENIMM2256   | and         |       |   | v |   |   |   | v |  | v |  |
|  | ENIVINISSSO | Manufacturi |       |   | Λ |   |   |   | Λ |  | Λ |  |
|  |             | ng          |       |   |   |   |   |   |   |  |   |  |
|  |             | Processes   |       |   |   |   |   |   |   |  |   |  |
|  | I ABB3260   | Laboratorie | Basic | v | v |   |   | v |   |  |   |  |
|  | LADK5200    | s 2         |       | Λ | Α |   |   | Λ |   |  |   |  |

| Fourth | MECH4261 | Mechanical<br>Design                       | Basic |   | x |   |   |   | X | X | X |  |
|--------|----------|--|-------|---|---|---|---|---|---|---|---|--|
|        | MSDE3459 | Mechatroni<br>c Systems<br>Design 1        | Basic |   | X | x | X | x | x | X | X |  |
|        | COIN1405 | Computer<br>Interfacing                    | Basic |   | X |   | X | X |   |   | X |  |
|        | ROIS3464 | Robotics<br>and<br>Intelligent<br>Systems  | Basic |   | X |   |   | x | x |   | X |  |
|        | DICO3460 | Digital<br>Control                         | Basic | X | x |   | X | X | x |   | X |  |
|        | MOCO3462 | Modern<br>Control 1                        | Basic | X | x |   | X | X | X |   | X |  |
|        | ARIR3463 | Artificial<br>Intelligence<br>for Robotics | Basic |   | X |   |   | x |   |   | X |  |
|        | LABR4260 | Laboratorie<br>s 1                         | Basic | X | X |   |   | X |   |   |   |  |
|        | POWE4267 | Power<br>Electronics                       | Basic | X | x |   | X | X | X |   | X |  |

|   | INDE1401 | Industrial<br>Engineering                    | Basic |   |   |   |   |   | X |   |   |  |
|---|----------|--|-------|---|---|---|---|---|---|---|---|--|
| - | MSDE3459 | Mechatroni<br>c System<br>Design 2           | Basic |   | x | x | X | x | x | X | x |  |
|   | SYID3465 | System<br>Identificatio<br>n                 | Basic |   | x |   |   | x | x |   | X |  |
|   | ROAU3464 | Robotics<br>and<br>Automation                | Basic |   | x | x | X | x |   |   | X |  |
|   | GPRO3461 | Project                                      | Basic |   | X | X | X | X | X | X | X |  |
|   | MOCO3462 | Modern<br>Control 2                          | Basic | X | X |   | X | x | X |   | X |  |
|   | DMRO3458 | Design and<br>Manufacturi<br>ng of<br>Robots | Basic |   | x |   |   | X |   |   | X |  |
|   | LABR4260 | Laboratorie<br>s 2                           | Basic | X | X |   |   | x |   |   |   |  |

