

الجامعة التكنولوجية
 قسم هندسة السيطرة والنظم
 مواد الامتحان التنافسي للعام الدراسي (2020-2021)
 تخصص ماجستير هندسة الحاسبات

تفاصيل المفردات	اسم المادة	ت
1. Register transfer and Micro-operation, 2. Register transfer language Bus and memory transfer, 3. Arithmetic logic shift unit, 4. Arithmetic logic, and shift micro-operations, Micro-programmed control unit, Control memory, Micro-program sequencer, 5. Design of control unit. 6. Central processing unit 7. General register organization, Stack organization, Memory stack, 8. Instruction format, 9. Addressing modes, 10. Types of interrupts. 11. Memory Systems 13. Input-output organization Peripheral devices, Modes of transfer, 14. Direct memory access (DMA), Priority interrupt. 15. Parallelism in uniprocessor system 16. Comparison between parallelism and pipelining Memory systems 3. Organization, interleaving (high order, low order), Local memory types. 17. Pipelining: General principles, Arithmetic pipeline, design example pipeline adder. 18. Pipeline analysis (timing, control): Reservation table, states, Collision & collision vector analysis, hardware initiation, State diagram, Modified state diagram, Micro-programmed pipeline. 19. Vector processing: Vector instruction, vector processor, Typical Hardware architecture	Advanced Computer Architecture (مرحلة ثالثة + رابعة)	1

<p>-Introduction</p> <ol style="list-style-type: none">1. What Operating Systems Do2. Computer-System Organization3. Computer-System Architecture4. Operating-System Structure5. Operating-System Operations6. Computing Environments7. Open-Source Operating Systems Processes <p>management</p> <ol style="list-style-type: none">1. Process Concept (the process, process state ,process control block)2. Operations on Processes3. Process Scheduling (long term, short term scheduling, scheduling queue)4. CPU scheduling5. Basic concepts (CPU & I/O Burst cycle, dispatcher, preemptive & non-preemptive scheduling)6. Scheduling Criteria7. Scheduling Algorithms8. FCFS, SJF, SRTF, RR,MLQ,MLFBQ <p>-Process Synchronization</p> <ol style="list-style-type: none">1. Background2. The Critical-Section Problem3. Peterson's Solution4. Mutex Locks5. Semaphores6. Classic Problems of Synchronization <p>-Deadlocks</p> <ol style="list-style-type: none">1. System Model2. Deadlock Characterization3. Methods for Handling Deadlocks4. Deadlock Prevention5. Deadlock Avoidance6. Deadlock Detection7. Recovery from Deadlock <p>-Main Memory</p>	<p>Operating System (OS) (المرحلة الرابعة)</p>	<p>2</p>
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<ol style="list-style-type: none"> 1. Background 2. Swapping 3. Contiguous Memory Allocation 4. Segmentation 5. Paging 		
<ol style="list-style-type: none"> 1. Network Types 2. Network Topology 3. Transmission Media 4. Network Components 5. The TCP/IP Protocol Layers: (Design Issues for the Layers) 6. The Link Layer 7. The Services Provided by the Link Layer, Error detection and Correction, Random Access Protocols 8. Transport-layer protocol 9. Transmission Control Protocol TCP (Connection Establishment), User Datagram Protocol UDP Network Layer (a) Routing Algorithms The Link-State (LS) Routing Algorithm Distance vector routing (b) IPv4 Addresses Classless Addressing Classful Addressing (c) Computer and Network Security 	<p>Computer Networks (مرحلة رابعة)</p>	<p>3</p>
<ol style="list-style-type: none"> 1. Neural networks (NNs) : -Artificial Neuron Types of Activation functions types of NNs (Feed-forward, Feedback, Supervised and Unsupervised), and types of recall. -Learning Algorithms: Hebbians, perceptron and delta learning rules. -Generalized delta learning rule (Error back propagation algorithm for single and multiple layers. 2. Fuzzy Logic (FL) : -Introduction, Fuzzy concepts, Fuzzy sets, and Fuzzy operations. -Fuzzification, Inference Engine, Rule-Base, and 	<p>Intelligent Control Systems (مرحلة رابعة)</p>	<p>4</p>

<p>Defuzzification, -Fuzzy Logic Control (FCL). 3.Binary Genetic Algorithm (GA) . - Elements of GA, Genetic Operators, Initialization, Coding, Fitness Function ,Selection, Crossover (Mating), and Mutation</p>		
<p>1.Sampled Data Control Systems Sampling and reconstruction, properties of sampled signal, ideal Sampler, Z.O.H. 2. Analysis of Discrete Control System Open-loop system, closed-loop system, system time-response, steady state error analysis, mapping S- plane /Z-plane. 3.Stability Analysis Bilinear transformation, Z into W, the Routh-Hurwitz criterion, and Jury's stability test. 4. Design of Digital Controllers Direct design controller, dead-beat controller, PID controller, Design and realization, response between sampling instants, discrete Time equivalent controller, Root locus, Modified Z- transform. 5. Time -Domain Analysis. Impulse Response and step response for LTI processors (systems). Digital convolution. Difference equations. 6. Frequency-Domain Analysis (I). Discrete Fourier Transform (DFT), DFT for periodic sequences, DFT for aperiodic digital sequence, DFT properties. Fast Fourier Transform (FFT). Frequency Response of LTI processor. 7. Frequency –Domain Analysis the Z-transform. Definition and properties of the Z-transform. Z-plane poles and Zeros. 8. Design of Recursive digital filter (IIR) Simple design based on Z-plane poles and zeros. Filters derived from analog designs.</p>	<p>Digital Control & DSP (مرحلة ثالثة + رابعة)</p>	<p>5</p>

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Frequency sampling filters.		
1. Introduction of variables, decisions, repeating a block of statements. and arrays. 2. Data structure Types, built in types, declaration types 3. Stack and queue Declaration, design functions, applications 4. Single linked list Declaration, design and applications 5. Graph and tree Declaration, design and applications	Database and data Structure in C++ (المرحلة الرابعة)	6
1. Calculus limit and continuity, Differentiation, Integration, Series and sequence 2. Partial derivative. 3. Vector valued function. 4. Double integral. 5. Fourier series and Laplace transform. 6. Ordinary differential equations first order, linear set of equations.	Mathematics I مرحلة اولى + ثانية	7
1. Linear algebra and Matrices Vector, Solution of linear equations, Matrices 2. Ordinary differential equations Series solution to ODE (power series solution, Legendre polynomial, Frobenius solution and Bessel's function) and Partial differential Equations. 3. Complex Analysis 4. Numerical Analysis	Mathematics II مرحلة ثالثة	8
Bipolar Junction Transistor (BJT) Construction, Operation, Characteristics, Configuration (C.E, C.B, C.C), Ratings. D.C. Biasing and Thermal Stability Biasing Techniques, Stability Factors, Effect of Temperature.		9

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Small Signal Analysis of BJT Amplifier H-parameters Mode, re-model, Equivalent Circuit, Voltage Gain, Current Gain, Input Impedance, Output Impedance. Field Effect Transistor (FET) Construction, Types, Characteristics, Biasing and D.C. Analysis. FET Amplifiers A.C. Analysis of Common Source, Common Drain,	Electronics I مرحلة ثانية	
8086 architecture. 8086 addressing modes. 8086 instruction set. Using stack in 8086. Embedded systems definition and sample applications. Common characteristics for embedded systems. Embedded systems main parts. CISC (Complex Instruction Set Computer) versus RISC (Reduced Instruction Set Computer). Microcontroller versus microprocessor. ATmega 169 microcontroller (architecture and capabilities)	Microprocessor and embedded systems مرحلة ثالثة + رابعة	10